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DYNAMICS OF AN IMAGE VIEWED THROUGH A ROTATING MIRROR

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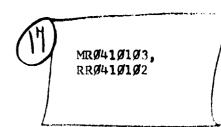
DYNAMICS OF AN IMAGE VIEWED THROUGH A ROTATING MIRROR

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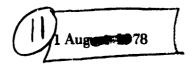
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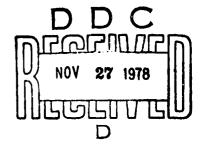
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### SUMMARY PAGE

### THE PROBLEM

It is frequently assumed that the virtual image of a target viewed through a rotating mirror moves with respect to the observer at twice the angular rate of mirror rotation. This assumption is false, and leads to imprecise treatment of open loop tracking systems. Of particular interest is a class of dynamic visual acuity experiments in which acuity targets are viewed through a rotating mirror, where control of image velocity, exposure time, and image dimensions are of critical importance.

## **FINDINGS**

Expressions are derived which describe the direction of the target image with respect to the observer as a function of mirror position. This relationship is nonlinear, and depends upon the distances from the center of rotation of the mirror (A) to the observer (C), and to the target (B), and upon the included angle  $(\angle BAC)$ . Expressions are further derived for image velocity, acceleration, mirror intercept, and image dimensions as functions of mirror position.

# **ACKNOWLEDGMENTS**

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### INTRODUCTION

A majority of the visual and optical scientists who have toured our vision laboratories during the past three years have been surprised at our statement that the ocular movement required to track an image viewed through a rotating mirror is a nonlinear function of the mirror movement. Although the surprise is quickly abated by a brief explanation, the frequency with which this fact is neglected, even in laboratory instrumentation, suggests the need for an explicit statement of the relationships involved.

The laws of reflection predict that the direction of a ray reflected by a rotating plane mirror will change at twice the rate of mirror rotation in a plane normal to the axis of rotation. Changes in mirror orientation will result in equal changes in both the angle of incidence and the angle of reflection of the ray. However, the sample of rays reflected from a target to an arbitrary tracker position changes as a function of mirror orientation. The angle of incidence of these samples is not a linear function of mirror orientation, but depends upon the relative positions of the target, mirror and tracker, as well as the orientation of the mirror.

These considerations are of importance, in general, to the design of open loop tracking systems in which a sensor views the virtual image of a target through a gimbaled mirror (1, 2) and, in particular, to the configuration of a class of dynamic visual acuity experiments in which the subject views an acuity target through a rotating mirror (3).

The purpose of this paper is to derive expressions of the relationships which determine the viewing angle as a function of mirror position, and to discuss some of the implications for stimulus control in visual experiments.

# IMAGE DIRECTION: $\omega = f(\theta)$

In a Cartesian coordinate system, let  $A_{(x_A, y_A)}$ ,  $B_{(x_B, y_B)}$ , and  $C_{(x_C, y_C)}$  represent the positions of the center of rotation of a plane mirror, a target, and the center of rotation of the eye, respectively, such that the plane of incidence is normal to the axis of rotation of the mirror. Let  $\theta$  and  $\omega$  represent the angular orientation of the mirror and the eye, respectively, as indicated in Figure 1. The position of the observed virtual image is located at  $p_{(x_B, y_B)}$  such that the following relationships hold: (a) line  $Bp \perp Ar$  at  $q_{(x_B, y_B)}$  such that line segments  $l_{Bq} = l_{qp}$ , and (b) line Cp intersects the mirror at point  $r_{(x_B, y_B)}$  such that  $\phi_1 = \phi_2 = \phi_3$ , and line segments  $l_{Br} = l_{rp}$ .

The problem is to define eye orientation ( $\omega$ ) as a function of mirror orientation ( $\theta$ ). The approach will be to define point  $p_{(x_p, y_p)}$  as a function of  $\theta$ ; then  $\omega$  will be defined as a function of line Cp.

Point  $q_{(x_q, y_q)}$  may be determined as a function of  $\theta$  in the following manner:

line 
$$Aq: y_q = y_A + (x_q - x_A) \tan \theta$$
 (1)

line 
$$Bq: y_q = y_B - (x_q - x_B) ctn \theta$$
 (2)

Subtracting and solving for  $x_a$ , we obtain

$$\mathbf{x}_{\mathbf{q}} = \frac{\mathbf{y}_{\mathbf{B}} - \mathbf{y}_{\mathbf{A}} + \mathbf{x}_{\mathbf{A}} \tan \theta + \mathbf{x}_{\mathbf{B}} \cot \theta}{\tan \theta + \cot \theta} . \tag{3}$$

Then,

$$y_{\mathbf{q}} = \frac{x_{\mathbf{B}} - x_{\mathbf{A}} + y_{\mathbf{B}} \tan \theta + y_{\mathbf{A}} \cot \theta}{\tan \theta + \cot \theta} . \tag{4}$$

Since line segment Bp is bisected at q

$$x_{\mathbf{p}} = x_{\mathbf{q}} + (x_{\mathbf{q}} - x_{\mathbf{B}}) \tag{5}$$

$$x_{\mathbf{p}} = \frac{2y_{\mathbf{B}} - 2y_{\mathbf{A}} + 2x_{\mathbf{A}} \tan \theta - x_{\mathbf{B}} \tan \theta + x_{\mathbf{B}} \cot \theta}{\tan \theta + \cot \theta}$$
(6)

and

$$y_{\mathbf{p}} = y_{\mathbf{q}} + (y_{\mathbf{q}} - y_{\mathbf{B}}) \tag{7}$$

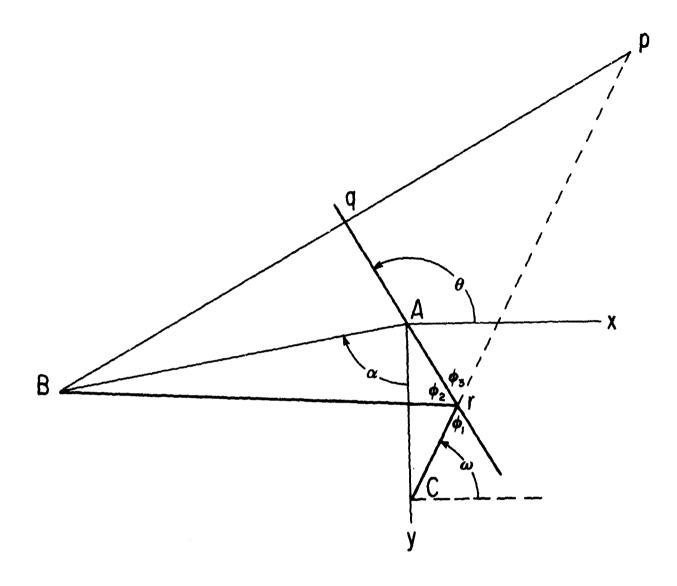


Figure 1. Geometry of the relationship between the target (B), the center of rotation (A) of mirror qAr, and the center of rotation of the eye (C), when viewing the target image (p). The image direction  $(\omega)$  with respect to the eye is a nonlinear function of the mirror angle  $(\theta)$ . Parameters of the relationship are the ratio of distances from center of rotation of the mirror to that of the eye  $(l_{CA})$  and to the target  $(l_{BA})$ , and the angle, BAC, between them  $(\alpha)$ .

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$$y_{\mathbf{p}} = \frac{2x_{\mathbf{B}} - 2x_{\mathbf{A}} + y_{\mathbf{B}} \tan \theta + 2y_{\mathbf{A}} \cot \theta - y_{\mathbf{B}} \cot \theta}{\tan \theta + \cot \theta}$$
(8)

then,

$$tan \omega = \frac{y_p - y_c}{x_p - x_c} \tag{9}$$

$$\tan \omega = \frac{(x_{\rm B} - x_{\rm A}) \sin 2\theta + (y_{\rm A} - y_{\rm B}) \cos 2\theta + y_{\rm A} - y_{\rm C}}{(y_{\rm B} - y_{\rm A}) \sin 2\theta + (x_{\rm B} - x_{\rm A}) \cos 2\theta + x_{\rm A} - x_{\rm C}}$$
(10)

No generality is lost by arbitrarily positioning  $A_{(0,0)}$  at the origin, and  $C_{(0,y_c)}$  on the y-axis. This allows equation (10) to be simplified

$$\tan \omega = \frac{x_{\rm B} \sin 2\theta - y_{\rm B} \cos 2\theta - y_{\rm C}}{y_{\rm B} \sin 2\theta + x_{\rm B} \cos 2\theta}. \tag{11}$$

IMAGE VELOCITY: 
$$\frac{d\omega}{d\theta} = f(\theta)$$

Since  $\frac{d\omega}{dt} = \frac{d\omega}{d\theta}$ .  $\frac{d\theta}{dt}$ , the angular velocity of the target image with respect to the eye may be obtained as the product of the mirror velocity and the derivative of equation (11).

$$\frac{d\omega}{d\theta} = \frac{2 \left[ y_{\rm C} (y_{\rm B} \cos 2\theta - x_{\rm B} \sin 2\theta) + x_{\rm B}^2 + y_{\rm B}^2 \right]}{2 y_{\rm C} (y_{\rm B} \cos 2\theta - x_{\rm B} \sin 2\theta) + x_{\rm B}^2 + y_{\rm B}^2 + y_{\rm C}^2}$$
(12)

$$\frac{d^2\omega}{d\theta^2} = \frac{4y_{\rm C}(x_{\rm B}^2 + y_{\rm B}^2 - y_{\rm C}^2) (y_{\rm B} \sin 2\theta + x_{\rm B} \cos 2\theta)}{\left[2y_{\rm C}(y_{\rm B} \cos 2\theta - x_{\rm B} \sin 2\theta) + x_{\rm B}^2 + y_{\rm B}^2 + y_{\rm C}^2\right]^2}$$
(13)

It is useful to express equations (11), (12), and (13) in terms of the angle BAC ( $\alpha$ ), and the distances from the center of rotation of the mirror to that of the eye ( $l_{CA}$ ), and to the target ( $l_{BA}$ ). From Figure 1, we see that

$$x_{n} = -l_{n} \sin \alpha \tag{14}$$

$$y_{\mathbf{B}} = -l_{\mathbf{B}\mathbf{A}} \cos \alpha \tag{15}$$

$$y_{\mathbf{C}} = -l_{\mathbf{C} \, \mathbf{A}} \tag{16}$$

Substituting these in equation (11), and employing the identities,

$$\cos (A + B) = \cos A \cos B - \sin A \sin B \tag{17}$$

$$\sin (A + B) = \sin A \cos B + \cos A \sin B \tag{18}$$

we obtain

$$tan \ \omega = \frac{l_{BA} \cos (\alpha + 2\theta) + l_{CA}}{-l_{BA} \sin (\alpha + 2\theta)}$$
 (19a)

$$= \frac{\cos (\alpha + 2\theta) + \frac{l_{CA}}{l_{BA}}}{-\sin (\alpha + 2\theta)}$$
 (19b)

$$\frac{d\omega}{d\theta} = \frac{2l_{BA}[l_{BA} + l_{CA} \cos (\alpha + 2\theta)]}{l_{BA}^2 + 2l_{BA}l_{CA} \cos (\alpha + 2\theta) + l_{CA}^2}$$
(20a)

$$= \frac{2 + 2 \frac{l_{CA}}{l_{BA}} \cos (\alpha + 2\theta)}{1 + 2 \frac{l_{CA}}{l_{BA}} \cos (\alpha + 2\theta) + \left(\frac{l_{CA}}{l_{BA}}\right)^2}$$
(20b)

$$\frac{d^2\omega}{d\theta^2} = \frac{4l_{BA}l_{CA}(l_{BA}^2 - l_{CA}^2) \sin(\alpha + 2\theta)}{\left[l_{BA}^2 + 2l_{BA}l_{CA}\cos(\alpha + 2\theta) + l_{CA}^2\right]^2}$$
(21a)

$$= \frac{4 \frac{l_{CA}}{l_{BA}} \left[ l - \left( \frac{l_{CA}}{l_{BA}} \right)^2 \right] \sin (\alpha + 2\theta)}{\left[ l + 2 \frac{l_{CA}}{l_{BA}} \cos (\alpha + 2\theta) + \left( \frac{l_{CA}}{l_{BA}} \right)^2 \right]^2}$$
(21b)

The physical limitations of the problem place the following constraints upon  $\theta$  and  $\alpha$  (see Figure 1):

$$90^{\circ} < \theta < 270^{\circ} \tag{22}$$

$$-90^{o} < \omega < 270^{o} \tag{23}$$

$$-180^{\circ} < \alpha < 180^{\circ} \tag{24}$$

It should be noted that the mirror angle ( $\theta$ ) and the tracker or eye angle ( $\omega$ ) are equal to  $\theta^0$  in the direction of the positive x-axis, and increase with counterclockwise rotation. The angle BAC ( $\alpha$ ) is equal to  $\theta^0$  in the direction of the negative y-axis, and increases in the clockwise direction.

Equation (12) has a minimum (if  $l_{\rm CA} < l_{\rm BA}$ ) or a maximum (if  $l_{\rm CA} > l_{\rm BA}$ ) when

$$y_{\mathbf{B}} \sin 2\theta + x_{\mathbf{n}} \cos 2\theta = 0; \tag{25a}$$

that is, when

$$\frac{\sin 2\theta}{\cos 2\theta} = -\frac{x_{\mathbb{R}}}{y_{\mathbb{R}}} = \tan 2\theta. \tag{25b}$$

From Figure 1 we see that

$$\frac{x_{\mathbf{B}}}{y_{\mathbf{B}}} = \tan \alpha . \tag{26}$$

Thus,  $\frac{d\omega}{d\theta}$  has a minimum (or maximum) when

$$tan 2\theta = -tan \alpha (27a)$$

$$= \tan (360^{\circ} - \alpha), \tag{27b}$$

or, when

$$\theta = 180^{\circ} - \frac{\alpha}{2} . \tag{28}$$

From equation (20b), we find the value of  $\frac{d\omega}{d\theta}$  at its minimum (or maximum) to be

$$\frac{d\omega}{d\theta} \underset{\text{min (or max)}}{=} \frac{2}{l + \frac{l_{CA}}{l_{RA}}}.$$
 (29)

The following limits upon the function  $\frac{d\omega}{d\theta} = f(\theta)$  are apparent from equations (20a) and (20b):

$$\lim_{l_{\mathbf{C}} \stackrel{\partial \omega}{\to 0}} \frac{d\omega}{d\theta} = 2 \tag{30}$$

$$\lim_{l_{\mathbf{B}} \stackrel{d}{\downarrow} 0} \frac{d\omega}{d\theta} = 0 \tag{31}$$

$$\lim_{\substack{l_{C} \uparrow l_{BA}}} \frac{d\omega}{d\theta} = 1 \tag{32}$$

# PARAMETERS: $\frac{l_{CA}}{l_{BA}}$ , $\alpha$

We see from equations (19b), (20b), and (21b) that the values of  $\omega$ ,  $\frac{d\omega}{d\theta}$ ,  $\frac{d^2\omega}{d\theta^2}=f(\theta)$  depend upon the ratio of  $l_{CA}$  to  $l_{BA}$ , and their included angle, rather than upon the individual values of these distances. Therefore, the parameters of these functions are taken to be  $\alpha$  and  $\frac{l_{CA}}{l_{BA}}$ .

In Figure 2, graphs of  $\frac{d\omega}{d\theta} = f(\theta)$  are presented for seven values of  $\frac{l_{CA}}{l_{BA}}$ , and for one value of  $\alpha$  ( $\alpha = 0$ ). For the purposes of these graphs it is assumed that the dimensions of the target and tracker are negligible, and that the tracker is capable of rotating \$60°.

The solid portions of the curves apply to values of  $\theta$  over which the target image may be observed through a rotating mirror of maximum length. That is, the center of rotation is on the mirror's midline, and half the mirror's length is equal to  $l_{CA}$  or  $l_{BA}$ , whichever is smaller. The dotted portions of the curves apply to an extended mirror whose angular movement is limited in one direction by the position of the target, and in the other by the position of the tracker  $(90^{\circ} < \theta < 270^{\circ} - \alpha)$ .

When  $\alpha=0$ , as in Figure 2, the tracker, target, and center of rotation of the mirror are all aligned. If  $\frac{l_{CA}}{l_{BA}} < 1$ , counterclockwise rotation of the mirror causes the target image to move from right to left, decelerating across the right side of the mirror through a minimum velocity at  $\theta=180^{\circ}-\frac{\alpha}{2}$ , and accelerating across the left side of the mirror. If the target is closer to the center of mirror rotation than is the tracker,  $\frac{l_{CA}}{l_{BA}} > l$ , the image moves first to the right, accelerating through  $\frac{d\omega}{d\theta}=0$ , then through a maximum at  $\theta=180^{\circ}-\frac{\alpha}{2}$ , and decelerates across the left side of the mirror. If  $\frac{l_{CA}}{l_{BA}}=1$ , then  $\frac{d\omega}{d\theta}=1$  over the applicable range of  $\theta$ 's.

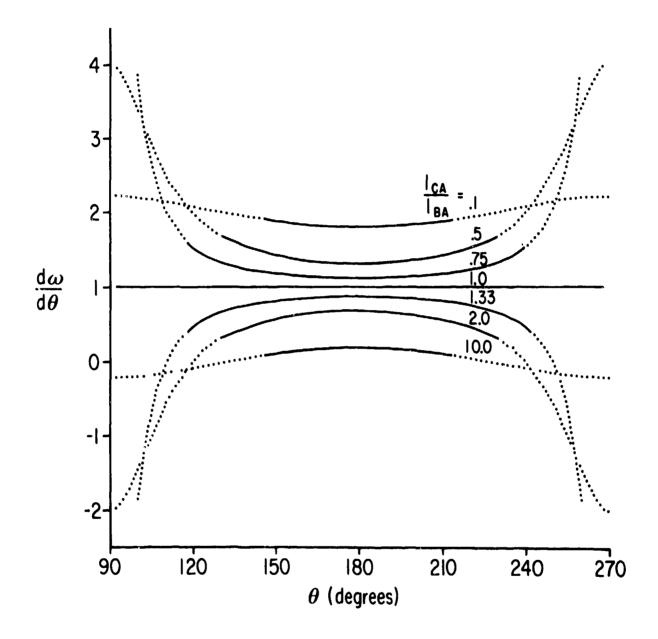


Figure 2. Rate of change of image direction with respect to mirror angle as a function of mirror position  $\left[\frac{d\omega}{d\theta} = f(\theta)\right]$  for seven values of  $\frac{l_{CA}}{l_{BA}}$  (0.1, 0.5, .75, 1.0, 1.33, 2.0, 10.0;  $\alpha = 0$ ).

When  $\alpha=0$ , this condition is equivalent to tracking one's own eye in a rotating mirror. In each case the minimum (or maximum) value of  $\frac{d\omega}{d\theta}$  is  $\frac{2}{1+\frac{l_{CA}}{l_{-}}}$  (equation (29)).

Reciprocal values of  $\frac{l_{CA}}{l_{BA}}$  produce curves which are symmetrical with respect to  $\frac{d\omega}{d\theta} = 1$ . This is apparent in Figure 2, and it may be proven by substituting reciprocal values for  $\frac{l_{CA}}{l_{BA}}$  in equation (20b):

$$\frac{2 + 2x \cos{(\alpha + 2\theta)}}{1 + 2x \cos{(\alpha + 2\theta)} + x^2} - 1 = 1 - \frac{2 + \frac{2}{x} \cos{(\alpha + 2\theta)}}{1 + \frac{2}{x} \cos{(\alpha + 2\theta)} + \frac{1}{x^2}}$$
(33)

Graphs of equations (20) and (21) are presented in Figure 3 for four values of  $\alpha$  and one value of  $\frac{l_{CA}}{l_{BA}}$ . The values represented by the curve on the right side of Figure 3(b) are the same as those represented by the uppermost curve of Figure 2;  $\frac{l_{CA}}{l_{BA}} = 0.1$  and  $\alpha = 0$  in both cases. The scale of the ordinate in Figure 3 is increased in order to better illustrate the effects of varying  $\alpha$ .

The value of  $\alpha$  determines the position of the curve along the abscissa, the minimum occurring at  $\theta = 180^{\circ} - \frac{\alpha}{2}$  (equation (28)). The value of  $\alpha$  does not alter the form of the curve, nor its symmetry with respect to the minimum  $\theta$ . The requirement for this symmetry may be proven by the following:

At 
$$\theta = 180^{\circ} - \frac{\alpha}{2}$$
,  
 $\cos (\alpha + 2\theta) = \cos (\alpha + 360^{\circ} - \alpha) = \cos 360^{\circ}$  (34)

and,

$$\cos (360^{\circ} + \psi_1) = \cos (360^{\circ} - \psi_1). \tag{35}$$

Thus, for values of  $\theta$  which are symmetrical with respect to the minimum, equation (20) predicts that

$$\frac{d\omega}{d\theta} = \frac{d\omega}{d\theta} \tag{36}$$

where,  $\psi_{i} = (180^{\circ} - \frac{\alpha}{2}) - \theta_{i}$ .

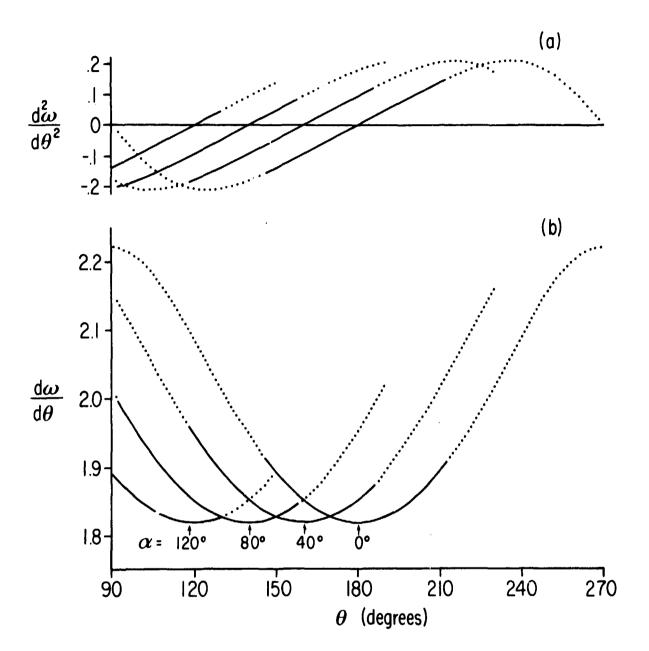


Figure 3. (a)  $\frac{d^2\omega}{d\theta^2} = f(\theta)$ . (b)  $\frac{d\omega}{d\theta} = f(\theta)$ . Rates of change of image direction with respect to mirror angle as functions of mirror position for four values of  $\alpha$  (0°, 40°, 80°, 120°;  $\frac{l_{CA}}{l_{A}} = 0.1$ ).

Thus, the function  $\frac{d\omega}{d\theta}=f(\theta)$  is symmetrical with respect to  $\theta=180^{\circ}-\frac{\alpha}{2}$ , and this symmetry is not influenced by the value of  $\alpha$ . However, the values of  $\theta$  for which the target image may be observed through a rotating mirror are determined, in part, by  $\alpha$ . The solid portions of the curves in Figure 3 apply to the values of  $\theta$  over which the target is observable through a rotating mirror of maximum length. The "observation window" for a given aperture shifts along the abscissa as a function of  $\alpha$ . When the midpoint of the aperture is on the axis of rotation, the window is symmetrical with respect to  $\theta=180^{\circ}-\frac{\alpha}{2}$  only when  $\alpha=0$ . For other values of  $\alpha$  the observation window is no longer centered on  $\theta=180^{\circ}-\frac{\alpha}{2}$ , but shifts in the direction of  $\alpha$  with respect to this point. The magnitude of  $\frac{d\omega}{d\theta}$  can easily exceed 2 for an extended mirror. However,  $\frac{d\omega}{d\theta} \le 2$  for all values of  $\theta$  which lie within the observation window of a rotating mirror  $(l_{Ar} < l_{CA})$ . The extent of the observation window depends upon the mirror aperture, which may be calculated once the mirror intercept,  $r_{(x_r)}, r_{(x_r)}$ , has been defined.

# MIRROR INTERCEPT: $r_{(x_*, y_*)}$

The coordinates of the point at which the principle incident ray is reflected on the mirror may be determined by the intercept of lines Ar and Cr:

line Ar: 
$$y_x = y_A + (x_x - x_A) \tan \theta$$
 (37)

line Cr: 
$$y_x = y_0 + (x_x - x_0) \tan \omega$$
 (38)

Setting point  $A_{(0,0)}$  at the origin and point  $C_{(0,y_C)}$  on the y-axis, and solving for the intercept, we obtain

$$x_{z} = \frac{y_{c}}{\tan \theta - \tan \omega} , \qquad (39)$$

$$y_{z} = \frac{y_{c} \tan \theta}{\tan \theta - \tan \omega} . \tag{40}$$

The length of line segment  $l_{Ax}$  is

$$l_{Ax} = \sqrt{x_x^2 + y_x^2} \quad . \tag{41}$$

Substituting equations (39) and (40),

$$l_{Ax} = \sqrt{\frac{y_C^2 (1 + \tan^2 \theta)}{(\tan \theta - \tan \omega)^2}}$$
 (42)

Employing the identity,

$$sec^2 \theta = 1 + tan^2 \theta , \qquad (43)$$

we obtain the magnitude of  $l_{Ax}$ :

$$l_{Ax} = \frac{y_{C} \sec \theta}{\tan \theta - \tan \omega} . \tag{44}$$

From Figure 1, it is clear that the mirror intercept is coincident with the center of rotation of the mirror  $(l_{Ar} = 0)$  when  $\omega = 90^{\circ}$ . From equation (19), we see that when  $\omega = 90^{\circ}$ ,

$$\sin (\alpha + 2\theta) = 0. \tag{45}$$

Within the physical limitations expressed by equations (22), (23), and (24), this relationship requires that  $\theta = 180^{\circ} - \frac{\alpha}{2}$ , which is the value of  $\theta$  at  $\frac{d\omega}{d\theta \min (mex)}$ .

Within the boundaries of the observation window, the aperture limits for any desired range of  $\theta$  may be calculated by substituting equation (19) in equation (44). When  $\frac{d\theta}{dt}$  is known, the resulting equation may be used to define the aperture limits which will provide a desired exposure time as is required, for example, in dynamic visual acuity experiments.

# IMAGE DISTANCE: $l_{Cp}$

The optical distance from the eye to the target image  $(l_{Cp})$  is equal to the sum of the distance from the eye to the point of reflection on the mirror  $(l_{Cp})$  and the distance from the mirror intercept to the target  $(l_{Bp})$ . These distances vary as the target is tracked across the rotating mirror.

From Figure 1, we see that

$$l_{C_{z}} = \sqrt{x_{z}^{2} + (y_{z} - y_{C})^{2}}$$
 (46a)

$$=\frac{y_{c} \sec \omega}{\tan \theta - \tan \omega} \tag{46b}$$

$$l_{Br} = \sqrt{(x_{r} - x_{B})^{2} + (y_{r} - y_{B})^{2}}$$
 (47)

$$l_{Cp} = l_{Cr} + l_{Br}. (48)$$

This distance is maximum when the target image is in alignment with the axis of rotation of the mirror ( $\omega = 90^{\circ}$ ,  $\theta = 180^{\circ} - \frac{\alpha}{2}$ ).

# IMAGE DIMENSIONS: $\Delta \tau$ , $\Delta \omega$

The angular size of the target image also undergoes change as a function of  $\theta$ . Both the vertical (parallel to axis of mirror rotation) and horizontal angular dimensions vary because of the changing image distance. The horizontal dimension undergoes further variation due to the nonlinearity of the function  $\omega = f(\theta)$  reflected in equation (19). The angular dimensions of the target image may be calculated for a given value of  $\theta$  in the following manner.

Let the target extend in two dimensions to a height,  $\Delta z$ , normal to the plane of incidence, and a width,  $\Delta w$ , normal to  $l_{BA}$  along the plane of incidence. The vertical angle subtended by the target image at the eye is given by

$$\Delta \tau = tan^{-1} \frac{\Delta z}{l_{Cp}} . \tag{49}$$

The horizontal angular subtense of a target of width  $\Delta w$  may be calculated with respect to the center of rotation of the mirror to be

$$\Delta \alpha = tan^{-1} \frac{\Delta w}{l_{BA}} . \tag{50}$$

Then, equation (19) may be employed to calculate the angular width of the target image with respect to the eye ( $\Delta \omega$ ).

$$\Delta \omega = \omega_{\alpha} - \omega_{\alpha} + \Delta \alpha \tag{51}$$

where

$$\omega_{\alpha + \Delta \alpha} = tan^{1} \frac{\cos (\alpha + \Delta \alpha + 2\theta) + \frac{l_{CA}}{l_{BA}}}{-\sin (\alpha + \Delta \alpha + 2\theta)}. \tag{52}$$

In Figure 4 are presented graphs representing angular subtense of the target image as a function of  $\theta$ , using two values of  $\alpha$  and two values of  $\frac{l_{CA}}{l_{BA}}$ . The solid lines represent the vertical dimension  $(\Delta \tau)$ , and the dotted lines represent the horizontal dimension  $(\Delta \omega)$ . The ranges of  $\theta$  for these plots represent the observation windows of a rotating mirror whose length is  $2l_{CA}$ , and for which  $l_{Ax~(max)} = l_{CA}$ . In Figure 4(a) and (b),  $\frac{l_{CA}}{l_{BA}} = 0.5$ , and  $\alpha = 0^0$ ,  $80^0$ , respectively. In Figure 4(c), both values of  $\alpha$  are represented for  $\frac{l_{CA}}{l_{BA}} = 0.1$ . Linear target sizes have been adjusted so that the minimum visual angle subtended is  $0.1^0$  for both values of  $\frac{l_{CA}}{l_{BA}}$ . Both the angular height and width of the target vary as a function of mirror orientation. These variations are symmetrical with respect to  $\theta = 180^0 - \frac{\alpha}{2}$ . The effects of changes in image distance with mirror rotation are seen in the plots of image height, the distance decreasing as  $\theta$  deviates from  $\theta = 180^0 - \frac{\alpha}{2}$ . However, the change in aspect angle with mirror rotation serves to retard the rate of change of the image width. Further, since image distance varies as a function of  $\omega$ , the target's angular height will not be uniform across its width, and this distortion in image height will vary as a function of  $\theta$ .

# **DISCUSSION**

The dynamic characteristics of an image viewed through a rotating mirror are governed by two parameters: the ratio of distances from the center of rotation of the mirror to that of the tracker, and to the target  $\left(\frac{l_{CA}}{l_{BA}}\right)$ , and the angular displacement of the target from the tracker with respect to the mirror's center

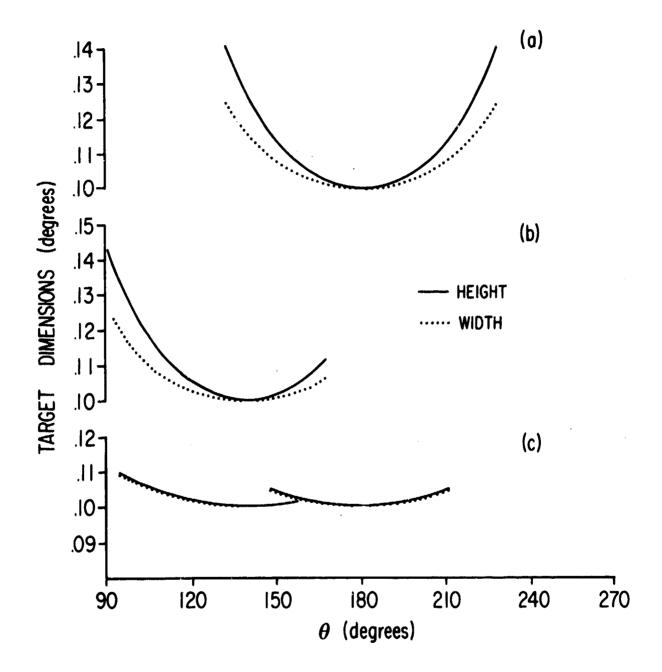


Figure 4. Angular dimensions of the target image as a function of mirror position. (a)  $\frac{l_{CA}}{l_{BA}} = 0.5$ ,  $\alpha = 0$ . (b)  $\frac{l_{CA}}{l_{BA}} = 0.5$ ,  $\alpha = 80^{\circ}$ . (c)  $\frac{l_{CA}}{l_{BA}} = 0.1$ ,  $\alpha = 80^{\circ}$ ,  $0^{\circ}$ . The minimum angle subtended by the target image in each case is  $0.1^{\circ}$ .

of rotation ( $\alpha$ ). The direction ( $\omega$ ) of the target image with respect to the tracker varies as a nonlinear function of mirror orientation ( $\theta$ ), as do the image distance ( $l_{Cp}$ ) and angular dimensions ( $\Delta \tau$ ,  $\Delta \omega$ ).

In general, when the plane of incidence is normal to the axis of mirror rotation, the function  $\frac{d\omega}{d\theta} = f(\theta)$  is nonlinear and is symmetrical with respect to  $\frac{l_{CA}}{l_{BA}} = l$  for reciprocal values of  $\frac{l_{CA}}{l_{BA}}$ . Further,  $\frac{d\omega}{d\theta} = f(\theta)$  has a minimum at  $\theta = 180^{\circ} - \frac{\alpha}{2} \left(\frac{d\omega}{d\theta_{\min}}\right) = \frac{2}{l_{BA}}$ , and is symmetrical with respect to that value of  $\theta$  for all values of  $\theta$  and  $\theta$ . This symmetry applies, as well, to variations in distance  $\theta$  and angular dimensions  $\theta$  of these variables as functions of mirror orientation  $\theta$ . Calculated values of these variables as functions of  $\theta$  are represented in Appendix A. The range of mirror orientations  $\theta$  over which the target image may be observed depends upon the aperture of the mirror. Thus, apertures may be designed to control that segment of the above functions which is to be observed.

It is frequently assumed that a target image viewed through a rotating mirror noves with respect to the observer at twice the angular rate of the mirror rotation. Equations (20) and (21) indicate this to be true only in the trivial case where  $\frac{l_{CA}}{l_{BA}} = 0$ . The only practical case in which  $\frac{d\omega}{d\theta} = f(\theta)$  is linear occurs when  $l_{CA} = l_{BA}$ ; then  $\frac{d\omega}{d\theta} = l$ , but the angular height of the target image changes dramatically.

The significance of these dynamic characteristics of the target image depends, of course, upon the application. In many cases, the small, dynamic changes encountered are acceptable. Then, it is required only that adjustments be made in estimates of mean values of image variables. Often, it is desired to maximize the size of the observation window, and to minimize accelerations and changes in image size. This need is served by minimizing  $\frac{l_{CA}}{l_{DA}}$  and  $\alpha$ . Maximizing  $l_{DA}$  is directly effective and free of complications. Problems in minimizing  $l_{CA}$  and  $\alpha$  derive from the dimensions of the tracker and its ability to obscure the target. One temptation may be to displace the target vertically. Resulting variations

in vertical angular displacement,  $\tau$ , as a function of mirror orientation may be calculated in the manner of equation (49).

Since  $\frac{d\omega}{dt} = \frac{d\omega}{d\theta}$ .  $\frac{d\theta}{dt}$ , the function  $\frac{d\omega}{dt}$  may be linearized exactly by adjusting the mirror speed,  $\frac{d\theta}{dt}$ , in accordance with equation (20).

# **SUMMARY**

1. 
$$\tan \omega = \frac{\cos (\alpha + 2\theta) + \frac{l_{CA}}{l_{BA}}}{-\sin (\alpha + 2\theta)}$$

- 2. for rotating mirror  $(l_{Ar} < l_{CA}, l_{BA})$ :  $0 < \frac{d\omega}{d\theta} < 2$
- 3. a.  $\lim_{l_{\mathbf{C}} \stackrel{\cdot}{\lambda} 0} \frac{d\omega}{d\theta} = 2$ ,  $\frac{d^2\omega}{d\theta^2} = 0$

b. 
$$\lim_{l_{\perp} \downarrow 0} \frac{d\omega}{d\theta} = 0$$
,  $\frac{d^2\omega}{d\theta^2} = 0$ 

c. 
$$\lim_{\substack{l_G \downarrow l_{BA}}} \frac{d\omega}{d\theta} = 1$$
,  $\frac{d^2\omega}{d\theta^2} = 0$ 

4. for 
$$\theta = 180^{\circ} - \frac{\alpha}{2}$$
,  $\frac{l_{CA}}{l_{BA}} < 1$ 

$$\frac{d\omega}{d\theta}_{\min} = \frac{2}{1 + \frac{l_{CA}}{l_{BA}}}$$

$$l_{Ax} = 0$$

$$\omega = 90^{\circ}$$

$$l_{CP_{\max}} = l_{CA} + l_{BA}$$

$$\Delta \tau_{\min}, \Delta \omega_{\min} = \frac{\Delta z}{l_{CA} + l_{BA}}$$

5. Symmetry: 
$$\frac{d\omega}{d\theta} - 1$$
 (for  $\frac{l_{CA}}{l_{BA}} = x$ ) =  $1 - \frac{d\omega}{d\theta}$  (for  $\frac{l_{CA}}{l_{BA}} = \frac{1}{x}$ )
$$\frac{d\omega}{d\theta} = \frac{d\omega}{d\theta} =$$

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# APPENDIX A

Calculated Values of  $\omega$ ,  $\frac{d\omega}{d\theta}$ ,  $\frac{d^2\omega}{d\theta^2}$ ,  $l_{Az}$ ,  $l_{Cp}$ ,  $\Delta \tau$ ,  $\Delta \omega$  as Functions  $\theta$ 

TABLE I

alculated Values of Variables related to the Observation a Target through a Rotating Mirror.  $l_{GA}=l$ ,  $l_{BA}=l\theta$ 

	•			3	38	3  • •  •		, c	۲۵	3 🗸
00 = 8	a = 400	a = 800	a = 1200							
188				-67.83815	2.28429	-0.28842	1.79856	9.36676	0.12132	0.24247
118				-46.81799	2,15547	-0.34675	1,78853	9.25630	9.11884	0.23710
120	166			-24.79128	2.88791	-0.41414	1.57459	9,53939	0.11531	0.22967
138	110			-4.27686	2.81518	-6.41881	1,39281	9.87558	0.11139	9.22166
140	120	189		15.52988	1.94761	-0.35736	1,16870	10.22128	0.10762	0.21424
158	138	110		34.71500	1.89189	-0.27834	9.98989	16,53565	8.18441	0.20811
160	140	129	188	53,41679	1.85109	-0.18813	0.62185	18,78522	6.18199	0.20362
178	158	130	118	71,79072	1.82642	-0.69433	9.31572	10.94584	P. 18858	8.28891
188	169	140 •	120 •	99.88888	1.81818	ଜ ଜନ୍ଧନ	9.99999	11.89999	9.18888	0.20000
198	170	159	130	198,20928	1.82642	0.69438	ĕ.31572	10.94584	9.16050	6.20091
200	180	160	146	126.58321	1.85109	0.18813	0.62185	10.78522	9.10199	0.20362
216	190	170	158	145,28500	1.89189	0.27834	9.98969	10.53565	0.19441	0.20811
228	288	186		164.47188	1,94761	6.35730	1.15870	10.22128	9.19762	8.21424
238	210	198		184.27686	2.01510	0.41001	1.39281	9.87558	0.11139	9.22166
240	228			204,79128	2.08791	3.41414	1.57459	9.53939	0.11531	9.22967
258	238			226.01799	2.15547	0.34675	1.78853	9.25638	0.11884	0.23710
260				247.83815	2.20429	6.20842	1.79056	9.86676	8.12132	B.24247

8 - 001 = 0

TABLE II

Calculated Values of Variables related to the Observation of a Target through a Rotating Mirror.  $l_{\rm GA}=l$ ,  $l_{\rm BA}=2$ 

	•			3	-3 -2	3 -	ا ا	lc.	۸۲	3
a = 60	0 <b>95</b> = 8	980 = D	a = 1200							
166				-52.12201	3.41696	-5.32793	1.31308	1.11418	0.26927	0.51254
110				-22,48426	2.54973	-4,11669	1.25292	1.39134	0.21562	9.38246
120	1 00			-6.88888	2.00000	-2,38948	1.15478	1.73205	0.17320	6.30008
130	118			18,33449	1.69688	-1.27507	1.02139	2.07495	9.14458	0.25452
140	1-20	100		34,37370	1.52682	-8.72885	8.85705	2.38633	9,12572	0.22902
158	138	110		49.18661	1.42857	-0.42418	9.66667	2.64575	9.11339	9.21429
169	148	120	1 679	63,08249	1.37202	-0.23722	9,45693	2.83975	8.18564	ĕ.2058A
178	158	138	118	76,63627	1.34251	-6.18788	6,23153	2.95952	9.10137	0.20138
180	168	140.	120.	96.66666	1.33333	9.00080	9.66686	3.83688	9.16668	8.29888
198	170	158	130	103,36373	1.34251	0.10788	0.23153	2.95952	0.10137	0.20138
286	180	168	140	116.91751	1.37202	0.23722	0.45603	2.83975	9.10564	9.20580
210	198	178	150	130.89339	1.42857	9.42418	6.66667	2.64575	0.11339	8.21429
228	200	186		145,62638	1.52682	6.72885	8.85785	2,38633	0.12572	P. 22902
238	218	198		161,66551	1.69680	1.27587	1.82139	2.87495	8.14458	8.25452
240	220;			180.00000	2.66698	2,38948	1.15478	1.73285	0.17320	9.39888
250	238			282,48426	2.54973	4.11669	1.25292	1.39134	9.21562	0.38246
268				232,12201	3.41696	5.32793	1.31308	1.11410	8.26927	0.51254
•	,									

TABLE III

Calculated Values of Variables related to the Observation of a Target through a Rotating Mirror.  $l_{\rm CA}=1$ ,  $l_{\rm BA}=1.3333$ 

	•			3	3 2	3 -	1,4.5	10.0	۲۵	3
g = 00	a = 40°	a = 800	$\alpha = 120^{\circ}$							
100				-29.81141	3.86015	-19.18724	1.12548	8.52144	0.44746	9.6755
110				-1.42818	2.85815	-4,93568	1.07392	0.85730	9.27217	9.36918
120	198			16.10326	1.53842	-1.72169	8.98973	1.20183	8.19415	6.26923
130	110			30,33882	1.33599	-0.76239	8.87547	1.52139	9.15337	0.23388
140	120	166		43,16587	1.23997	-6.38892	8.73461	1.80021	0.12961	9.21796
150	130	118		55.28548	1.18917	-0.21254	0.57142	2.82756	6.11508	6.20811
168	140	120	188	67.02380	1.16133	-9.11473	88868.6	2.19555	9.18627	0.20323
178	158	138	118	78.55717	1.14719	-6.05082	9.19845	2,29858	6.18151	9.20876
186	168	140	120	99.86999	1.14284	0.88888	ତ . ଜଡ଼ଜନ	2,33330	0.19090	6.2000
196	178	158	130	101.44283	1.14719	9.05882	0.19845	2,29858	8.18151	8.20076
200	180	160	140	112.97620	1.16133	9.11473	8.39888	2.19555	8.18627	0.20323
210	190	170	158	124.71460	1.18917	0.21254	0.57142	2.82756	ĕ.11588	9.20811
220	288	180		136.83493	1.23997	8.38892	0.73461	1.80921	0.12961	6.21788
230	210	198		149.66118	1.33599	0.76239	9.87547	1.52139	0.15337	8.23388
249	220			163,39674	1.53842	1.72169	6.98973	1.20183	0.19415	0.26923
258	230		·	181.42818	2.05815	4.93568	1.07392	0.85730	9.27217	0.36018
268			•	209.01141	3.86015	19.18724	1.12548	9.52144	9.44746	9.6755

TABLE IV

Calculated Values of Variables related to the Observation of a Target through a Rotating Mirror.  $l_{cA}=1,\ l_{bA}=1$ 

	•			3	3 -	3 -	ټي	ق	<b>Δ</b>	3
8:	a = 40	a = 86°	a= 120º		<u> </u>					
100				10.00000	1.00000	0.00000	6.98481	0.34730	9.57586	0.26969
110				20.00888	1.88888	8.99668	6,93969	0.68484	8.29238	0.2000
120	186			39.68888	1.66688	6.88888	0.86683	1.00068	6.26666	0.28889
136	110			40.58080	1.88888	9.88888	9.76684	1.28558	9.15557	3.26086
140	120	196		58.88888	1.66666	6.66966	9.64279	1.53209	8.13854	0.29999
150	136	119		69.99888	1.88888	9.88888	0.50000	1.73205	9.11547	9.2000
168	140	128	199	78.88888	1.88888	6.86868	6.34282	1.87939	9.16642	9.28898
170	150	130	110	86.86868	1.08868	6.66668	0.17365	1.96962	9.10154	9.28999
180	168	148*	128	99.08889	1.06689	8.99999	9.66668	2.66660	6.18888	0.28988
198	170	150	136	166.98686	1.86686	9.99699	0.17365	1.96962	9.18154	6.28998
200	188	168	146	118.88888	1.86668	8.66666	0.34202	1.87939	8.18642	0.2000
210	198	170	158	120.00000	1.06668	9.88888	0.50000	1.73205	0.11547	6.2000
228	200	186		130.00000	1.88888	9.66666	0.64279	1.53289	8.13854	8.29888
238	210	198		140.00600	1.88688	9.66688	8.76684	1,28558	9.15557	6.2000
249	228			159.88888	1.88888	8.88888	9.86683	1.98888	8.28888	9.28888
250	238			168.66896	1.88888	998989	6,93969	8.68484	8.29238	0.26868
268				170.66666	1.00600	8.88688	0.98481	8.34738	9.57586	8.28988

**A-4** 

TABLE V

Calculated Values of Variables related to the Observation of a Target through a Rotating Mirror.  $l_{\rm cA}=l,\ l_{\rm bA}=.75$ 

	•			3	3 8	3.0	l <sub>Ar</sub>	le,	۵۲	3
a = 0°	$\alpha = 40^{\circ}$	$\alpha = 80^{o}$	$a = 120^{\circ}$							
166				49.01381	-1.36028	19.18621	0.84412	8.39118	क्षेत्र विश्व	-8,43487
110				41.42985	-0.05821	4,93578	0.80545	9.64299	A.27217	-8.81359
128	188			43.89789	0.45154	1.72180	0.74231	0.30129	0.19414	9,19769
138	110			49.66199	6.56399	9,76245	0.65661	1.14106	9.15337	9.15493
140	120	106		56,83551	9.76981	9.38395	0.55696	1.35017	0.12951	9.17733
150	130	110		64.71500	9.81881	9.21255	0.42857	1.52069	3.11508	0.18919
168	146	128	199	72,97646	9.83865	B.11474	0.29316	1.64668	9.18627	0.19569
178	158	130	116	81.44295	6.85279	9.95882	6.14884	1,72396	0.10151	3.19898
189	160	148	120	59.99969	0.85714	ଓ. ଉତ୍ରଶ୍ୱ	9.99999	1.75998	3.18886	8.20000
198	178	150	130	98.55705	9.85279	-0.05982	0.14884	1.72396	0.10151	2.19898
200	186	160	170	107.02354	8.83865	-0.11474	0.29316	1.64668	6.10627	9.19569
210	150	170	150	115.28588	6.31831	-0.21255	0.42857	1.52069	9,11508	0.18919
228	200	186		123,15449	9.76891	-8.38895	9.55896	1.35017	0.12961	<b>9.17733</b>
230	219	198		130.33801	6,66399	- 6,76245	9.65661	1.14106	8.15337	8 15493
240	228			136, 10211	9.46154	-1,72188	0.74231	0.90139	9.19414	9.10769
258	238			138,57815	-0.05821	-4.93578	0.80545	8.64299	B. 27217	-3.81359
260				136,98619	-1.86020	-19,18621	0.84412	6.3911B	6,44744	-8.43487
= 1800 - 0										

TABLE VI

Calculated Values of Variables related to the Observation of a Target through a Rotating Mirror.  $l_{\rm cA}=l,\,l_{\rm BA}=.75$ 

186					3	-3 -8	3 . <b>3</b>	,,, ,,,	*°	Δ τ	3
186	a = 0°	$\alpha = 40^{\circ}$	$\alpha = 80^{\circ}$	a= 120º							
196         1.0.54975         -4.11669         0.62546         6.69967         0.21556         -6.215697         0.21569         -6.216699         -6.09699         2.38949         0.57735         0.86693         0.17329         -7.2567         0.56693         0.17329         0.17329         0.17329         0.17329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11329         0.11323         0.11329         0.11329         0.11323         0.11329         0.11329         0.11323         0.11329         0.11323         0.11323         0.11323         0.11323         0.11329	99:				72,12201	-1,41696	5.32793	Ø.65654	6.55705	8.26927	-2.42508
160         36,00000         -3,00000         2,30940         0,57735         0,86603         0,17320           110         61,6551         0,30320         1,27507         0,51070         1,03747         0,14458           120         160         55,62630         0,47318         0,72885         0,42853         1,19317         0,12572           130         110         7,989339         0,5749         0,23722         0,22891         1,41587         0,10554           140         120         6,833677         0,65749         0,1877         1,47976         0,10564           150         130         96,63627         0,65749         0,1877         1,47976         0,10564           170         150         130         96,63627         0,65749         0,1877         1,47976         0,10564           180         140         105,88249         0,65749         0,1877         1,47976         0,10564           180         140         105,88249         0,65789         0,1877         1,41987         0,10564           190         160         140         105,88249         0,65789         0,12885         0,13288         0,11339           200         180         160	118				62,48426	-8.54973	4,11669	0.52546	6,69567	0.21562	-8.1649E
110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110         110 <td>120</td> <td>196</td> <td></td> <td></td> <td>60.00608</td> <td>-9.09699</td> <td>2,38948</td> <td>0.57735</td> <td>0.86683</td> <td>0.17320</td> <td>କ୍ଷାନ୍ତ ଓଡ଼</td>	120	196			60.00608	-9.09699	2,38948	0.57735	0.86683	0.17320	କ୍ଷାନ୍ତ ଓଡ଼
120         180         55.62630         0.47318         0.72885         0.42853         1.19317         0.12572           130         110         79.89339         0.57143         0.42418         0.33333         1.32288         0.11332           140         120         76.91751         0.62798         0.23722         0.22801         1.41587         0.10564           150         130         110         6.62798         0.10700         0.11577         1.47976         0.10564           160         140         120         90.0000         0.65749         0.10700         0.11577         1.47976         0.10137           180         140         130         96.63627         0.65749         -0.18700         0.11577         1.47976         0.10137           180         140         135.88249         0.65749         -0.12722         0.22801         1.41937         0.10564           190         170         135.88249         0.57143         -0.42418         0.32333         1.32288         0.11339           200         180         114.37379         0.47318         -0.72885         0.42863         0.16663         0.16660         0.960600         0.56666         0.56669         0.114458	138	110			61,65551	8.38328	1,27507	0.51070	1.03747	₩.14458	3.63896
136         110         79.89339         0.57143         0.42418         0.33333         1.32288         0.11339           146         120         160°         76.91751         0.62798         0.23722         0.22801         1.41587         0.10564           150         130         110         63.36573         0.65749         0.10700         0.11577         1.47976         0.10137           170         150         120°         90.00000         0.65667         0.18700         0.11577         1.47976         0.10300           170         150         130         96.63627         0.65749         -0.18700         0.11577         1.47976         0.10300           180         160         140         195.08249         0.65798         -0.23722         0.22801         1.41937         0.10564           200         180         103.10661         0.57143         -0.42418         0.32333         1.32288         0.11339           210         180         114.37379         0.47318         -0.72805         0.51669         0.56669         0.51735         0.86669         0.11339           220         180         180         115.31574         -0.54973         -0.11669         0.52646	149	128	166		65,62638	0.47318	9.72885	0.42853	1.19317	0.12572	3.14195
146         120         120         120         53.36272         0.23722         0.22801         1.41587         0.10564           150         130         110         53.36272         0.65749         0.10700         0.11577         1.47976         0.10137           160°         140°         120°         90.60000         0.65749         0.10700         0.10700         0.10900         0.10900           178         150         130         96.63627         0.65749         -0.23722         0.22801         1.41987         0.10664           190         170         140         105.08249         0.65743         -0.42418         0.32288         0.11339           200         180         170         114.37379         0.472885         0.42853         1.19317         0.11552           210         190         115.33449         0.30320         -1.27507         0.51070         1.03747         0.14458           220         120.00000         0.90000         -2.30940         0.52646         0.69567         0.21562         -2.5565           230         127.51574         -0.54973         -4.11669         0.65654         0.55705         0.21562         -2.536793	158	138	11.0		79,89339	0.57143	9.42418	9.33333	1.32288	ø, 11339	9.17143
156         130         110         53.35372         0.65749         0.10730         0.11577         1.47976         0.108137           160         140         120         99.0000         0.65749         -0.1070         0.10877         1.47976         0.108137           170         150         130         96.63627         0.65749         -0.23722         0.22801         1.41937         0.108564           180         160         140         195.08249         0.65749         -0.23722         0.22801         1.41937         0.108564           200         170         150         193.10661         0.57143         -0.42418         0.33333         1.32288         0.11339           200         180         114.37379         0.47318         -0.72885         3.42853         1.19317         0.12572           216         190         115.33449         0.36328         -1.27507         0.51070         1.03747         0.13520         -1.27507         0.62646         0.69567         0.21562         -1.3320           230         127.51574         -0.54973         -1.11669         0.65654         0.55705         0.22567         0.22567	168	146	128	(S)	76,91751	0.62798	0.23722	0.22891	1.41587	9.10564	9,18839
168°         143°         120°         90.00000         0.66667         0.80000         0.30000         1.50000         0.10000           178         150         130         96.63627         0.65749         -0.1070         0.11577         1.47976         0.10137           180         160         140         105.08249         6.5773         -0.23722         0.22801         1.41937         0.10564           190         170         109.10661         0.57143         -0.42418         0.33333         1.32288         0.11339           200         180         114.37379         0.47318         -0.72885         0.42853         1.19317         0.14458           216         190         115.33449         0.36320         -1.27507         0.51669         0.56660         0.14458           220         120.00000         -0.50000         -2.30940         0.52646         0.69567         0.21562         -           230         117.51574         -0.54973         -4.11669         0.65664         0.55705         0.26567         0.26556         0.26556         0.26567         0.26567         0.26567         0.26567         0.26567         0.26567         0.26567         0.26567         0.26567         0.26567	170	158	130	911	63,36373	6,65749	9.16788	9.11577	1.47976	9.10137	2.19724
178         158         138         96.63627         6.55749         -0.1870         0.11577         1.47976         0.10137           180         160         140         195.88249         6.52798         -0.2372         6.22801         1.41987         0.10564           200         178         150         109.10661         0.57143         -0.42418         0.33333         1.32288         0.11339           200         180         114.37379         0.47318         -0.72885         3.42853         1.19317         0.12572           216         190         115.33449         0.36329         -1.27507         0.51070         1.03747         0.14458           220         120.00000         -0.00000         -2.30940         0.57735         0.86603         0.17320           230         117.51574         -0.54973         -4.11669         0.62646         0.69567         0.21562         -           230         117.51579         -1.41696         -5.32793         0.65654         0.55705         0.26927         -	188	168	148	120	99,99999	6.66667	ର, ଓଡ଼େଉଡ	ଜ. ଉଷ୍ଟେଶ	1.50000	9.19999	4.20008
186         168         146         135.08249         6.62798         -0.23722         6.22801         1.41987         6.18564           190         170         150         109.10661         0.57143         -0.42418         0.3333         1.32288         0.11339           200         180         114.37379         0.47318         -0.72885         0.42853         1.19317         0.12572           21e         190         115.33449         0.36329         -1.27507         0.51079         1.63747         0.14458           22e         12e.00009         -9.90009         -2.3094e         0.57735         0.86603         0.17329         -           23e         117.51574         -0.54973         -4.11669         0.62646         0.69567         0.21562         -           23e         107.87799         -1.41696         -5.32793         0.65654         0.55705         0.26927         -	198	178	158	130	96.63627	6.65749	-8.18789	6.11577	1.47976	6.18137	9.19724
196       178       158       109.10661       0.57143       -0.42418       0.33333       1.32288       0.11339         208       188       114.37379       0.47318       -0.72885       0.42853       1.19317       0.12572         216       190       115.33449       0.36326       -1.27507       0.51070       1.093747       0.14458         220       120.60000       -0.90000       -2.30940       0.57735       0.86603       0.17320       -         230       117.51574       -0.54973       -4.11669       0.62646       0.69567       0.21562       -         230       107.87799       -1.41696       -5.32793       0.65654       0.55705       0.26927       -	200	186	160		195, 98249	6.62798	-6,23722	6.22801	1.41987	9.18564	0.18839
200       180       114.37379       0.47318       ~0.72885       0.42853       1.19317       0.12572         210       190       115.33449       0.30320       -1.27507       0.51070       1.003747       0.14458         220       120.00000       -0.00000       -0.00000       -0.00000       -0.11669       0.62646       0.69567       0.21562         230       117.51574       -0.54973       -4.11669       0.65654       0.55705       0.26927	218	190	170	150	199,18661	0.57143	-0.42418	Ø.33333	1.32288	6.11339	0.17143
216       198       113.33449       0.30320       -1.27507       0.51070       1.03747       0.14450         220       120.00000       -0.00000       -2.30940       0.57735       0.86603       0.17320         230       117.51574       -0.54973       -4.11669       0.62646       0.69567       0.21562         107.87799       -1.41696       -5.32793       0.65654       0.55705       0.26927	228	200	180		114,37379	0.47318	-6,72885	8,42853	1.19317	0.12572	ð.14195
220 120.00000 -0.00000 -2.30940 0.57735 0.86603 0.17320 230 117.51574 -0.54973 -4.11669 0.62646 0.69567 0.21562 107.87799 -1.41696 -5.32793 0.65654 0.55705 0.26927	230	216	198		118,33449	0.30320	-1.27597	0.51070	1.03747	0.14458	9,89896
23 <b>8</b> 117.51574 -0.54973 -4.11669 0.62646 0.69567 0.21562 107.87799 -1.41696 -5.32793 0.65654 0.55705 0.26927	240	220			120.66666	-0.00696	-2.38948	6.57735	8.86683	0.17320	-6.86866
107.87799 -1.41696 -5.32793 0.65654 0.55705 0.26927	258	238			117,51574	-0.54973	-4.11669	0.62646	9.69567	Ø.21562	-8.16492
	268				107.87799	-1,41696	-5,32793	0.65654	9.55785	8.26927	-0.42508

. 0 = 1800 - 9

TABLE VII

Calculated Values of Variables related to the Observation of a Target through a Rotating Mirror.  $l_{cA} = l, l_{bA} = .l$ 

3		9.22467	-0.17899	-0.89669	-0.01661	0.05761	9.11898	9.16377	0.19091	8.19997	8.19091	0.16377	0.11890	0.05761	-8.01661	-6.89669	-0.17099	-0.22467	
۸		0.12132	0.11884 -	0.11531 -	6.11139	9.10762	0.16441	6.10199	6.18958	9.16666	6.16059	6.10199	8.18441	9.19762	- 0.11139	6.11531 -	6.11884 -	6,12132	
**************************************		8.98668	0.92563	0.95394	9.98756	1.02212	1.05357	1.07852	1.09450	1.10000	1.89458	1.87852	1.05357	1.02212	9.98756	0.95394	0.92563	89986.8	
lan.		3.17986	9.17885	9.15746	0.13928	6.11687	0.89891	0.06219	8.93157	6.66666	8.83157	0.86219	6.63691	6.11687	0.13928	9.15746	0.17085	8.17986	
3 -		9.20042	9.34675	0.41414	0.41001	0.35730	0.27834	9.18813	0.09433	0.09060	-0.09438	-6.18813	-0.27834	-0.35730	-9.41981	-0.41414	-8.34675	-0.20042	
-3 -8		-0.20429	-0.15547	16288.8-	-8.81518	0.05239	0.19811	0.14891	0.17358	9.18182	8.17358	0.14891	0.10811	0.05239	-8.01519	-8.88791	-0.15547	-8.28429	
, <b>3</b>		87.83815	86.81799	84.79128	84.27686	84.47188	85.28588	86.58321	88.20928	90.66660	91.79872	93.41679	94.71588	95.52900	95.72314	95.20872	93.98201	92.16185	
	$\alpha = 120^{\circ}$							106	110	120	130	140	158						
	$\alpha = 800$					166	119	120	138	140	150	160	178	186	190				
•	a= 400			166	118	120	138	140	158	168	170	188	198	266	210	228	238		
	σ0 = v	166	110	120	130	140	158	160	170	180	198	288	218	228	238	240	258	268	

A · 7

• • =  $180^0 - \frac{\alpha}{2}$ 

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REPORT DOCUMENTATION F		READ INSTRUCTIONS SEFORE COMPLETING FORM						
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19. KEY WORDS (Continue on reverse side it necessary and Dynamic Visual Acuity Open Loop Tracking Rotating Mirror Image Velocity Target Velocity								
It is frequently assumed that the variety mirror moves with respect to the observation is false, and leads in ir Of particular interest is a class of Dynstargets are viewed through a rotating many time, and image dimensions are of critical controls.	virtual image of a river at twice the ari imprecise treatment amic Visual Acuity	target viewed through a rotating ngular rate of mirror rotation. of open loop tracking systems. experiments in which acuity						

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20.

Expressions are derived which describe the direction of the target image with respect to the observer as a function of mirror position. This relationship is nonlinear, and depends upon the rotation of the mirror (A) to the observer (C), and to the target (B), and upon the included angle ( $\mathcal{L}$  BAC). Expressions are further derived for image velocity, acceleration, mirror intercept, and image dimensions as functions of mirror position.

21. 912

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